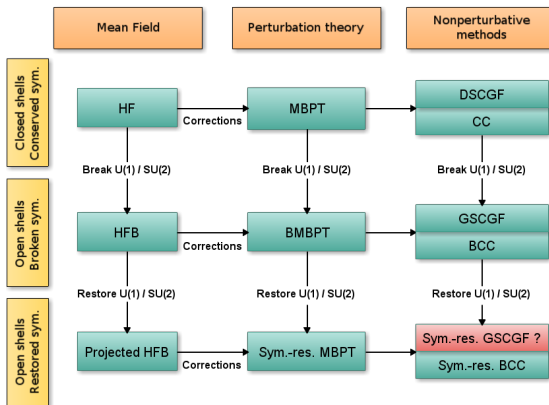


Spherical reduction of tensor networks in nuclear many-body theory: Automated symbolic angular-momentum algebra

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Progress in Ab Initio Techniques in Nuclear Physics
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Courtesy of P. Arthuis, T. Duguet

New methods recently proposed and implemented

- BMBPT [Tichai *et al.* 2018]
- GSCGF, BCC [Somà *et al.* 2011, Signoracci *et al.* 2014]
- Sym.-res. BCC & sym.-res. BMBPT [Duguet 2015, Duguet *et al.* 2017, Qiu *et al.* 2017]

Many-body calculations employ **mode-n tensors** and compute **tensor networks**

Input: Mode-n tensors

- Mode-2 tensor: t_{pq} , kinetic energy (Storage N^2)
- Mode-4 tensor: v_{pqrs} , two-body force (Storage N^4)
- Mode-6 tensor: w_{pqrst} , three-body force (Storage N^6)

where $pq\dots \in \mathcal{H}^{(1)}$ of dimension N .

Output: Tensor networks

$$E_0 = E_0^{HF} + \frac{1}{2} \sum_{ijab} \bar{v}_{ijab} t_i^a t_j^b + \frac{1}{4} \sum_{ijab} \bar{v}_{ijab} t_{ij}^{ab} \quad (\text{Evaluation } N^4)$$

Second-order triple amplitude in BCC theory

$$t_{k_1 k_2 k_3 k_4 k_5 k_6}^{60(2)} = P(k_1 k_2 k_3 / k_4 k_5 k_6) \sum_{k_7} \frac{\Omega_{k_1 k_2 k_3 k_7}^{31} t_{k_7 k_4 k_5 k_6}^{40(1)}}{E_{k_1 k_2 k_3 k_4 k_5 k_6}} \quad (20 \text{ terms})$$

State-of-the-art calculations !

- ◇ Storage/handling of full **mode-6 tensors** impossible in $\mathcal{H}^{(1)}$ (N^6)
- ◇ Evaluation of **tensor networks** CPU intensive (N^7)

Need to **reduce the dimensionality** of the problem !

- ◇ Use of symmetry in **spherical basis**

MScheme: Indices of tensors from spherical basis, $k = (n_k l_k j_k t_k m_k)$
 (In $e_{max} = 12$, dimension $N = 1820$)

JScheme: Indices of tensors from coupled basis, $\tilde{k} = (n_k l_k j_k t_k)$
 (In $e_{max} = 12$, effective dimension $\tilde{N} = 182 \ll N$)

MScheme tensors are expressed as a function of their **JScheme** equivalent:

$$\begin{aligned}
 t_{k_1 k_2 k_3 k_4}^{40(1)} &= (-1)^{j_{k_3} + m_{k_3} + j_{k_4} + m_{k_4}} \sum_{JM} J_{\tilde{t}_{k_1 \tilde{k}_2 \tilde{k}_3 \tilde{k}_4}}^{40(1)} \begin{pmatrix} j_{k_1} & j_{k_2} & J \\ m_{k_1} & m_{k_2} & M \end{pmatrix} \begin{pmatrix} j_{k_3} & j_{k_4} & J \\ -m_{k_3} & -m_{k_4} & M \end{pmatrix} \\
 \Omega_{k_1 k_2 k_3 k_4}^{31} &= (-1)^{j_{k_3} + m_{k_3}} \sum_{JM} J_{\tilde{\Omega}_{\tilde{k}_1 \tilde{k}_2 \tilde{k}_3 \tilde{k}_4}}^{31} \begin{pmatrix} j_{k_1} & j_{k_2} & J \\ m_{k_1} & m_{k_2} & M \end{pmatrix} \begin{pmatrix} j_{k_3} & j_{k_4} & J \\ -m_{k_3} & m_{k_4} & M \end{pmatrix} \\
 j_{\tilde{t}_{k_1 \tilde{k}_2 J_{12} \tilde{k}_3 \tilde{k}_4 \tilde{k}_5 J_{45} \tilde{k}_6}}^{60(2)} &= \sum_{m_{k_1} \dots m_{k_6}} m_{M_{12} M_{45}} (-1)^{j_{k_4} + m_{k_4} + j_{k_5} + m_{k_5} + j_{k_6} + m_{k_6}} t_{k_1 k_2 k_3 k_4 k_5 k_6}^{60(2)} \\
 &\quad \times \begin{pmatrix} j_{k_1} & j_{k_2} & J_{12} \\ m_{k_1} & m_{k_2} & M_{12} \end{pmatrix} \begin{pmatrix} J_{12} & j_{k_3} & j \\ M_{12} & m_{k_3} & m \end{pmatrix} \begin{pmatrix} j_{k_4} & j_{k_5} & J_{45} \\ -m_{k_4} & -m_{k_5} & M_{45} \end{pmatrix} \begin{pmatrix} J_{45} & j_{k_6} & j \\ M_{45} & -m_{k_6} & m \end{pmatrix}
 \end{aligned}$$

Second-order triple amplitude in BCC theory (Third term)

$$\left(\hat{t}_{k_1 k_2 k_3 k_4 k_5 k_6}^{60(2)} \right)_3 = - \sum_{k_7} \frac{\Omega_{k_3 k_1 k_4 k_7}^{31} \hat{t}_{k_2 k_7 k_6 k_5}^{40(1)}}{E_{k_1 k_2 k_3 k_4 k_5 k_6}}$$

Resulting **summation over magnetic quantum numbers**:

$$\sum_{m_1 m_2 m_3 m_4 m_5 m_6 m_7 m M_{12} M_{45} M^{(1)} M^{(2)}} \hat{J}_{12} \hat{J}_{45} \hat{j}^2 J^{(1)2} J^{(2)2}$$

$$\begin{pmatrix} j_1 & j_2 & J_{12} \\ m_1 & m_2 & -M_{12} \end{pmatrix} \begin{pmatrix} J_{12} & j_3 & j \\ M_{12} & m_3 & -m \end{pmatrix} \begin{pmatrix} j_4 & j_5 & J_{45} \\ m_4 & m_5 & M_{45} \end{pmatrix} \begin{pmatrix} J_{45} & j_6 & j \\ -M_{45} & m_6 & m \end{pmatrix}$$

$$\begin{pmatrix} j_3 & j_1 & J^{(1)} \\ -m_3 & -m_1 & M^{(1)} \end{pmatrix} \begin{pmatrix} j_4 & j_7 & J^{(1)} \\ -m_4 & m_7 & -M^{(1)} \end{pmatrix} \begin{pmatrix} j_2 & j_7 & J^{(2)} \\ -m_2 & -m_7 & M^{(2)} \end{pmatrix} \begin{pmatrix} j_6 & j_5 & J^{(2)} \\ -m_6 & -m_5 & -M^{(2)} \end{pmatrix}$$

Definition of a Yutsis Graph

- It is a **cubic** graph, i.e. each **node** has three **edges**.
- Each **node** represents a **3-j symbol**.
- Each **edge** represents **angular-momentum indices** (j, m).
- Node **sign** is $+$ if indices are in **trigonometric** order else $-$.
- Edge **orientation** goes from **positive** projection to **negative** one.

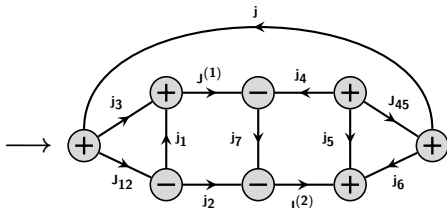
$$\sum$$

$$m_1 m_2 m_3 m_4 m_5 m_6 m_7 m M_{12} M_{45} M^{(1)} M^{(2)}$$

$$\begin{pmatrix} j_1 & j_2 & J_{12} \\ m_1 & m_2 & -M_{12} \end{pmatrix} \begin{pmatrix} J_{12} & j_3 & j \\ M_{12} & m_3 & -m \end{pmatrix} \begin{pmatrix} j_4 & j_5 & J_{45} \\ m_4 & m_5 & M_{45} \end{pmatrix}$$

$$\begin{pmatrix} J_{45} & j_6 & j \\ -M_{45} & m_6 & m \end{pmatrix} \begin{pmatrix} j_3 & j_1 & J^{(1)} \\ -m_3 & -m_1 & M^{(1)} \end{pmatrix} \begin{pmatrix} j_4 & j_7 & J^{(1)} \\ -m_4 & m_7 & -M^{(1)} \end{pmatrix}$$

$$\begin{pmatrix} j_2 & j_7 & J^{(2)} \\ -m_2 & -m_7 & M^{(2)} \end{pmatrix} \begin{pmatrix} j_6 & j_5 & J^{(2)} \\ -m_6 & -m_5 & -M^{(2)} \end{pmatrix}$$



[JR, A. Tichai, in prep.]

Reduction of a 2-cycle

$$= a \times (2a + 1)^{-1} \delta(a, b)$$

Reduction of a 3-cycle

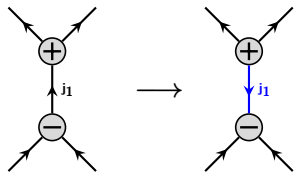
$$= \begin{matrix} i \\ \uparrow \\ \bullet \\ \swarrow \quad \searrow \\ k \quad j \end{matrix} + j \times \begin{Bmatrix} i & j & k \\ a & b & c \end{Bmatrix}$$

Reduction of a 4-cycle

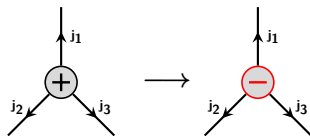
$$= \sum_f (-1)^{f+b-d} (2f+1) \begin{Bmatrix} i & l & f \\ d & b & a \end{Bmatrix} \begin{Bmatrix} j & k & f \\ d & b & c \end{Bmatrix} \times \begin{matrix} i \\ \swarrow \quad \searrow \\ l \quad k \end{matrix} + f \begin{matrix} j \\ \swarrow \quad \searrow \\ \quad k \end{matrix}$$

[D. Van Dyck, V. Fack, Discrete Mathematics]

Line reversal of internal line



Direct change of Node Sign



Phase associated to **Line reversal** of an internal line:

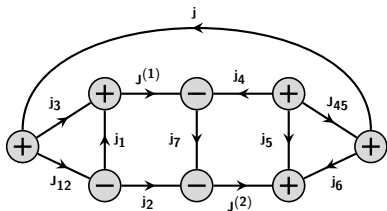
- $\phi_{lr} = (-1)^{2j}$

Phase associated to direct change of **Node Sign**:

- $\phi_{ns} = (-1)^{j_1+j_2+j_3}$

ReduceYutsisGraph(YutsisGraph Y)

```
1: while Y  $\neq$  triangular delta do  
2:   if Y has bubble then  
3:     Format and remove arbitrary bubble  
4:   else if Y has triangle then  
5:     Format and remove arbitrary triangle  
6:   else if Y has square then  
7:     Format and remove arbitrary square  
8:   else  
9:     //Implement higher-order rules  
10:  end if  
11: end while  
12: return formula
```



$$- (-1)^{j_1+j_2+J_{12}}$$

$$\left\{ \begin{matrix} j & J^{(1)} & j_2 \\ j_1 & J_{12} & j_3 \end{matrix} \right\} \left\{ \begin{matrix} j & j_4 & J^{(2)} \\ j_7 & j_2 & J^{(1)} \end{matrix} \right\} \left\{ \begin{matrix} j & J_{45} & j_6 \\ j_5 & J^{(2)} & j_4 \end{matrix} \right\}$$

All in all this gives the **J-coupled** version of second-order triple amplitude:

$$\left(j \tilde{t}_{\tilde{k}_1 \tilde{k}_2 J_{12} \tilde{k}_3; \tilde{k}_4 \tilde{k}_5 J_{45} \tilde{k}_6}^{60(2)} \right)_3 = (-1)^{j_1+j_2+J_{12}} \hat{J}_{12} \hat{J}_{45} \sum_{\tilde{k}_7 J^{(1)} J^{(2)}} \frac{J^{(1)} \tilde{\Omega}_{\tilde{k}_3 \tilde{k}_1 \tilde{k}_4 \tilde{k}_7}^{31} J^{(2)} \tilde{t}_{\tilde{k}_2 \tilde{k}_7 \tilde{k}_6 \tilde{k}_5}^{40(1)}}{E_{\tilde{k}_1 \tilde{k}_2 \tilde{k}_3 \tilde{k}_4 \tilde{k}_5 \tilde{k}_6}} \times J^{\hat{(1)}}{}^2 J^{\hat{(2)}}{}^2 \left\{ \begin{matrix} j & J^{(1)} & j_2 \\ j_1 & J_{12} & j_3 \end{matrix} \right\} \left\{ \begin{matrix} j & j_4 & J^{(2)} \\ j_7 & j_2 & J^{(1)} \end{matrix} \right\} \left\{ \begin{matrix} j & J_{45} & j_6 \\ j_5 & J^{(2)} & j_4 \end{matrix} \right\}$$

The full process has been **implemented in Python** !

First results for second-order triple amplitude:

$$\begin{aligned}
 & J \tilde{T}_{\vec{k}_1 \vec{k}_2 J_{12} \vec{k}_3 \vec{k}_4 \vec{k}_5 J_{45} \vec{k}_6}^3 \\
 &= \sum_{n_{k_7}} \hat{j}_{k_7}^{-2} J_{12}^{(0)} J_{45}^{(0)} J_{12}^{(0)} \tilde{H}_{\vec{k}_1 \vec{k}_2 \vec{k}_3 n_{k_7} (l_j t)_{J(0)}}^{31} J_{45}^{(0)} \tilde{T}_{\vec{k}_6 n_{k_7} (l_j t)_{J(0)} \vec{k}_4 \vec{k}_5}^2 \\
 &+ \sum_{\vec{k}_7 J^{(2)}} (-1)^{j_{k_4} + j_{k_5} + J_{45}^{(0)}} J_{12}^{(0)} J_{45}^{(0)} J^{(2)} J_{12}^{(0)} \tilde{H}_{\vec{k}_1 \vec{k}_2 \vec{k}_5 \vec{k}_7}^{31} J^{(2)} \tilde{T}_{\vec{k}_3 \vec{k}_7 \vec{k}_6 \vec{k}_4}^2 \left\{ \begin{matrix} j_{k_3} & j_{k_7} & J^{(2)} \\ j_{k_5} & J^{(0)} & J_{12}^{(0)} \end{matrix} \right\} \left\{ \begin{matrix} j_{k_6} & j_{k_4} & J^{(2)} \\ j_{k_5} & J^{(0)} & J_{45}^{(0)} \end{matrix} \right\} \\
 &+ \sum_{\vec{k}_7 J^{(1)} J^{(2)}} (-1)^{j_{k_1} + j_{k_2} + J_{12}^{(0)}} J_{12}^{(0)} J_{45}^{(0)} J^{(1)} J^{(2)} J^{(1)} \tilde{H}_{\vec{k}_3 \vec{k}_1 \vec{k}_4 \vec{k}_7}^{31} J^{(2)} \tilde{T}_{\vec{k}_2 \vec{k}_7 \vec{k}_6 \vec{k}_5}^2 \left\{ \begin{matrix} j_{k_3} & j_{k_1} & J^{(1)} \\ j_{k_2} & J^{(0)} & J_{12}^{(0)} \end{matrix} \right\} \left\{ \begin{matrix} j_{k_2} & j_{k_7} & J^{(2)} \\ j_{k_4} & J^{(0)} & J^{(1)} \end{matrix} \right\} \left\{ \begin{matrix} j_{k_6} & j_{k_5} & J^{(2)} \\ j_{k_4} & J^{(0)} & J_{45}^{(0)} \end{matrix} \right\} \\
 &+ \dots
 \end{aligned}$$

Spherical reduction of tensor networks:

- ◇ **Dimensionality reduction** going from MScheme to JScheme
- ◇ By hand **derivation tedious** in advanced formalisms
- ◇ Need for an **automatic tool**

Python implementation has already been used for:

- ◇ Normal ordering
- ◇ (P)BMBPT
- ◇ (P)BCC

Ongoing projects:

- ◇ Particle-number conserving normal ordering
- ◇ Shift invariance for PBMBPT
- ◇ ODE version of PBMBPT



Spherical reduction of tensor networks in nuclear many-body theory: Automated symbolic angular-momentum algebra

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Purpose of this work

- Push *ab initio* many-body calculations based on expansion methods:
 - developing new formalisms (PIMBSP, PBCG),
 - including many-body forces,
 - aiming for a higher accuracy.
- Automatize the spherical reduction of tensor networks:
 - developing a symbolic code for MScheme to JScheme reduction,
 - that operates over Clebsch-Gordan (CG) coefficients,
 - via a graphical representation of CG coefficients and reduction rules.

Tensor and tensor networks

Input: Matrix tensors

- Mode-2 tensor: $h_{\alpha\beta}$ kinetic energy (Storage N^2)
 - Mode-4 tensor: $h_{\alpha\beta\gamma\delta}$ two-body force (Storage N^4)
 - Mode-6 tensor: $h_{\alpha\beta\gamma\delta\epsilon\zeta}$ three-body force (Storage N^6)
- where $\alpha\beta \dots \in N^{(1)}$ of dimension N .

Output: Tensor networks

- Ex: $E_0 = E_0^{(0)} + \sum_{\alpha\beta\gamma\delta} h_{\alpha\beta\gamma\delta} \langle \alpha\beta | \alpha\beta \rangle + \sum_{\alpha\beta\gamma\delta\epsilon\zeta} h_{\alpha\beta\gamma\delta\epsilon\zeta} \langle \alpha\beta\gamma | \alpha\beta\gamma \rangle$ (Evaluation N^6)
- Storage handling of full mode-6 tensors impossible in N^6 (N^6)
 - Evaluation of tensor networks CPU intensive (N^6)
 - Need to reduce the dimensionality of the problem!

Symmetry reduction from MScheme to JScheme

- MScheme: Indices of tensors from spherical basis, $\hat{k} = (\hat{n}_1, \hat{l}_1, \hat{m}_1)$
($\hat{n}_1 \hat{m}_1 = 12$, dimension $N = 18(2)$)
- JScheme: Indices of tensors from coupled basis, $\hat{j} = (\hat{n}, \hat{l}, \hat{m})$
($\hat{n} \hat{m}_m = 12$, effective dimension $\hat{N} = 18(2) \ll N$)

- MScheme tensors are expressed as a function of their JScheme equivalents:

$$h_{\alpha\beta\gamma\delta}^{(000)} = (-1)^{(\hat{n}_1 + \hat{m}_1 + \hat{m}_2 + \hat{m}_3)} \sum_{\hat{j}_1, \hat{j}_2} h_{\hat{j}_1, \hat{j}_2}^{(000)} \begin{pmatrix} \hat{n}_1 & \hat{l}_1 & \hat{m}_1 \\ \hat{n}_2 & \hat{l}_2 & \hat{m}_2 \\ \hat{n}_3 & \hat{l}_3 & \hat{m}_3 \end{pmatrix} \begin{pmatrix} \hat{n} & \hat{l} & \hat{m} \\ \hat{n}_1 & \hat{l}_1 & \hat{m}_1 \\ \hat{n}_2 & \hat{l}_2 & \hat{m}_2 \\ \hat{n}_3 & \hat{l}_3 & \hat{m}_3 \end{pmatrix}$$

Ex: Second-order triple amplitude in BCC theory

$$\langle \alpha\beta\gamma | \alpha\beta\gamma \rangle = \sum_{\hat{j}_1, \hat{j}_2} h_{\hat{j}_1, \hat{j}_2}^{(000)} \begin{pmatrix} \hat{n}_1 & \hat{l}_1 & \hat{m}_1 \\ \hat{n}_2 & \hat{l}_2 & \hat{m}_2 \\ \hat{n}_3 & \hat{l}_3 & \hat{m}_3 \end{pmatrix} \begin{pmatrix} \hat{n} & \hat{l} & \hat{m} \\ \hat{n}_1 & \hat{l}_1 & \hat{m}_1 \\ \hat{n}_2 & \hat{l}_2 & \hat{m}_2 \\ \hat{n}_3 & \hat{l}_3 & \hat{m}_3 \end{pmatrix} \quad (1 \text{ of } 20 \text{ terms})$$

Representation of CG networks as a Yutsis Graph

Definition of a Yutsis Graph

- It is a cubic graph, i.e. each node has three edges.
- Each node represents a $3j$ symbol.
- Each edge represents angular-momentum indices (j, m) .
- Node sign is $+$ if indices are in trigonometric order else $-$.
- Edge orientation goes from positive projection to negative one.



Algorithm for Yutsis Graph reduction

Simplification rules



Reduce YutsisGraph(YutsisGraph Y)

- while Y != triangular delta do
- if Y has bubble then
 - Form and remove arbitrary bubble
- else if Y has triangle then
 - Form and remove arbitrary triangle
- else if Y has square then
 - Form and remove arbitrary square
- else
 - Templament higher-order rules
- end if
- end while
- return formula

J-coupled version of second-order triple amplitude

- Reduce the Yutsis Graph associated to the expression
- Put back resulting factors into JScheme expression

$$\langle \alpha\beta\gamma | \alpha\beta\gamma \rangle = (-1)^{(\hat{n}_1 + \hat{m}_1 + \hat{m}_2 + \hat{m}_3)} \sum_{\hat{j}_1, \hat{j}_2} h_{\hat{j}_1, \hat{j}_2}^{(000)} \begin{pmatrix} \hat{n}_1 & \hat{l}_1 & \hat{m}_1 \\ \hat{n}_2 & \hat{l}_2 & \hat{m}_2 \\ \hat{n}_3 & \hat{l}_3 & \hat{m}_3 \end{pmatrix} \begin{pmatrix} \hat{n} & \hat{l} & \hat{m} \\ \hat{n}_1 & \hat{l}_1 & \hat{m}_1 \\ \hat{n}_2 & \hat{l}_2 & \hat{m}_2 \\ \hat{n}_3 & \hat{l}_3 & \hat{m}_3 \end{pmatrix}$$

Summary

- State-of-the-art many-body methods require large storage capacities and are CPU intensive.
- Symmetry reduction: Reduction of the dimensionality going from MScheme to JScheme.
- Python code written for automated symbolic manipulation of Yutsis Graph.
- Application to more and more complex tensor networks.
- The code has already been used for: Normal ordering, (P)IMBSP, (P)BCG.

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