

Extrapolating Nuclear Many-Body Calculations with Constrained Gaussian Processes

Peter Gysbers M. Gennari, W. Fedorko, P. Navrátil

TRIUMF Ab Initio Workshop 2020



Context: Ab Initio Nuclear Theory

Goal: solve the nuclear eigenvalue problem

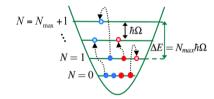
$$H\ket{\Psi_k} = E_k\ket{\Psi_k}$$
 , where $H = \sum_i^A T_i + \sum_{i < j} V_{ij} + \sum_{i < j < f} V_{ijf} + \cdots$

with nucleons as the degrees of freedom

The No-core Shell Model

Expand in anti-symmetrized products of harmonic oscillator single-particle states

$$|\Psi_k\rangle = \sum_{N=0}^{N_{max}} \sum_{j} c_{Nj}^k |\Phi_{Nj}\rangle$$

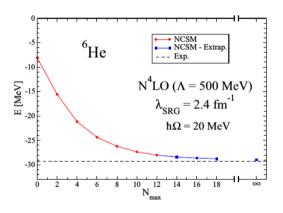


Calculations should converge to the exact value as $N_{max} \rightarrow \infty$

Motivation

- ightharpoonup Computational complexity grows exponentially with basis size parameter N_{max}
- ► The functional form of convergence curve is not known
- Ad hoc extrapolation:

$$E = E_{\infty} + \alpha \exp(-bN_{max})$$

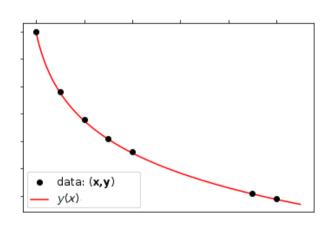


Goal: predict value at $N_{max} \to \infty$ with a meaningful error bar

Problem Statement

Given some data $\mathbf{y}=y(\mathbf{x}),$ find the underlying function y(x), i.e. predict $\mathbf{y}^*=y(\mathbf{x}^*)$

 $y \sim E$ $x \sim N_{max}$



x

Gaussian Processes

Key Assumption (Prior):

y and y* are drawn from a joint Gaussian distribution

$$p\left(\begin{bmatrix}\mathbf{y}\\\mathbf{y}^*\end{bmatrix}\right) = \mathcal{N}\left(\begin{bmatrix}\mu\\\mu_*\end{bmatrix}, \begin{bmatrix}C & C_*\\C_*^T & C_{**}\end{bmatrix}\right)$$

Make predictions by conditioning on data:

$$p(\mathbf{y}^*|\mathbf{y}) = \mathcal{N}(\mu_*, \Sigma_*)$$

where

$$\mu_* = C_*^T C^{-1} \mathbf{y}$$

$$\Sigma_* = C_{**} - C_*^T C^{-1} C_*$$

$$C = C[\mathbf{y}, \mathbf{y}]$$
$$= r(\mathbf{x}, \mathbf{x})$$

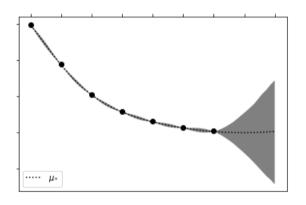
$$C_* = C[\mathbf{y}, \mathbf{y}^*]$$

$$= r(\mathbf{x}, \mathbf{x}^*)$$

$$C_{**} = r(\mathbf{x}^*, \mathbf{x}^*)$$

Gaussian Processes give a distribution of predictions (within error band)

Problem: Error bars blow up outside of data!



Idea: Use information about derivatives

Using Derivatives

- ► The derivative of a Gaussian process is a Gaussian process
- ▶ i.e. $\mathbf{y'}_i \equiv \frac{\mathrm{d}y}{\mathrm{d}x}|_{x=x'_i}$ is also jointly Gaussian distributed (as is $\mathbf{y''}$)

$$p\left(\begin{bmatrix} \mathbf{y}^* \\ \mathbf{y}' \\ \mathbf{y}'' \end{bmatrix} \middle| \mathbf{y} \right) = \mathcal{N}(\nu, \Sigma)$$

(ν and Σ are more complicated (see Extra Slides))

We want the posterior distribution:

$$p\left(\begin{bmatrix} \mathbf{y}^* \\ \mathbf{y}' \\ \mathbf{y}'' \end{bmatrix} \middle| \mathbf{y} \right) \times p(\mathbf{y}', \mathbf{y}'') = \mathcal{N}(\nu, \Sigma) \times m(\mathbf{y}') \times n(\mathbf{y}'')$$

Use SMC!

Sequential Monte-Carlo / Particle Filter

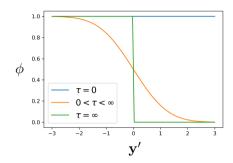
Draw N samples ("particles": $\begin{bmatrix} \mathbf{y}^* \\ \mathbf{y}' \\ \mathbf{y}'' \end{bmatrix}$) from a GP

for τ_1, τ_2 from 0 to ∞ :

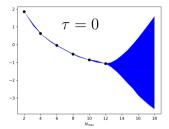
- for each particle:
 - ▶ propose new $\begin{bmatrix} \mathbf{y}^* \\ \mathbf{y}' \\ \mathbf{y}'' \end{bmatrix}$ values "nearby" old values
 - ▶ accept or reject according to

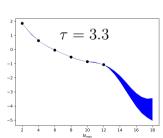
$$p\left(\begin{bmatrix} \mathbf{y}^* \\ \mathbf{y}' \\ \mathbf{y}'' \end{bmatrix} \middle| \mathbf{y} \right) \times p(\mathbf{y}', \mathbf{y}'' \middle| \tau_1, \tau_2) = \mathcal{N}(\nu, \Sigma) \times \phi(-\tau_1 \mathbf{y}') \times \phi(\tau_2 \mathbf{y}'')$$

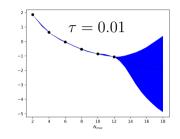
► resample: throw away "bad" particles and keep multiple copies of "good" particles (weighted by constraints)

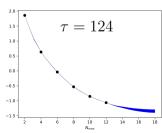


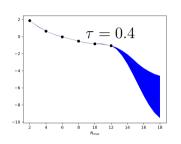
Results: He⁴

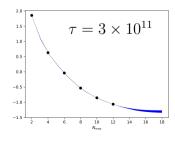




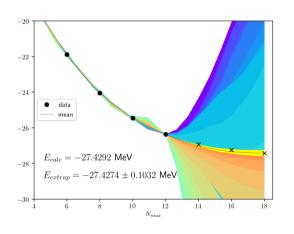


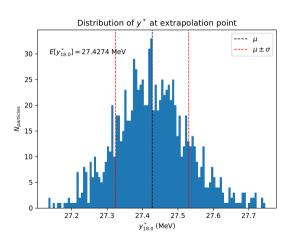




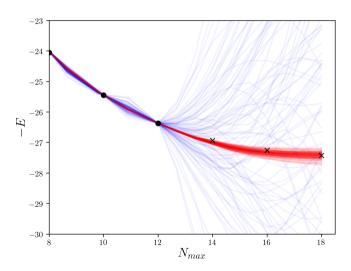


Results: He⁴

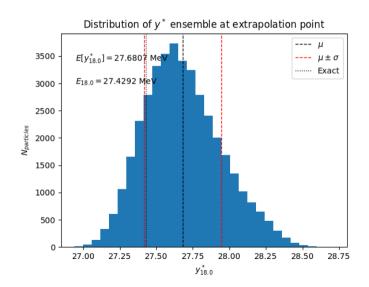




Results: He⁴



Results: He⁴, Ensemble of SMC Runs



Summary

Demonstrated viability of extrapolation by constrained Gaussian processes

Recent Progress

- ▶ Re-factored code
- ► Tuned SMC schedules give better results

Next Steps

- ► Test reproducibility
- ► Add "far-point" constraint: $y' \rightarrow 0$ at high N_{max}
- ► Try "log-kernels"



Thank you Merci



Extra Slide: Including Derivatives

$$p\left(\begin{bmatrix}\mathbf{y}\\\mathbf{y}^*\\\mathbf{y}'\\\mathbf{y}''\end{bmatrix}\right) = \mathcal{N}\left(\begin{bmatrix}\mu\\\mu_*\\\mu_1\\\mu_2\end{bmatrix},\begin{bmatrix}C&C_*&C_1&C_2\\C_*^T&C_{**}&C_{1*}&C_{2*}\\C_1^T&C_{*1}&C_{11}&C_{12}\\C_2^T&C_{*2}&C_{21}&C_{22}\end{bmatrix}\right)$$
 then

 $C_{*1} = C[\mathbf{y}^*, \mathbf{y}']$

 $C_{22} = C[\mathbf{v''}, \mathbf{v''}]$

 $= \frac{\partial}{\partial x_i} r(\mathbf{x}^*_i, \mathbf{x}'_j)$

 $= \frac{\partial^2}{\partial x_i^2} \frac{\partial^2}{\partial x_i^2} r(\mathbf{x''}_i, \mathbf{x''}_j)$

15/16

$$p\left(\begin{bmatrix}\mathbf{y}^*\\\mathbf{y}'\\\mathbf{y}''\end{bmatrix}|\mathbf{y}
ight)=\mathcal{N}(
u,\Sigma)$$

 $\Sigma = \begin{bmatrix} C_{**} & C_{1*} & C_{2*} \\ C_{*1} & C_{11} & C_{12} \\ C_{*2} & C_{21} & C_{22} \end{bmatrix} - [C_{*}, C_{1}, C_{2}]C^{-1} \begin{bmatrix} C_{*} \\ C_{1} \\ C_{2} \end{bmatrix}$

$$p \left(\begin{bmatrix} \mathbf{y} \\ \mathbf{y}'' \end{bmatrix} \right)$$

 $\nu = [C_*, C_1, C_2]C^{-1}\mathbf{y}$





Extra Slide: Constraints on Derivatives

Weight probability of samples:

$$p(\mathbf{y}^*|\mathbf{y}) \sim \mathcal{N}(\mu_*, \Sigma_*) \times m(\mathbf{y}') \times n(\mathbf{y}'')$$

based on criteria:

$$m(\mathbf{y}') = \sum_{i} \left(m(y_i') = \begin{cases} 1 & \text{if } y_i' < 0 \\ 0 & \text{otherwise} \end{cases} \right)$$
$$n(\mathbf{y}'') = \sum_{i} \left(n(y_i'') = \begin{cases} 1 & \text{if } y_i'' > 0 \\ 0 & \text{otherwise} \end{cases} \right)$$

How to compute derivatives?